

GPS Navigator

- Instrument -



Installation and Operation Manual
English



Introduction

Thank you for choosing NX2 GPS Navigator instrument. We are convinced that you will appreciate all the valuable information either you are a cruiser or a racer. It is important that you are following this instruction regarding installation and operation.

If the instrument are to be used in a Nexus Network, there are some systems settings that are dependent on where the transducers are installed, i.e. at the instrument or at the Server.



This manual is written for NX2 GPS Navigator instrument version 2.01 – 2.10
Edition: March 2007

1	Part specifications	5
2	INTRODUCTION	7
2.1	Basic Features	8
2.1.1	Position (POS)	8
2.1.2	Navigation (NAV)	8
2.1.3	Waypoint (WP)	8
2.1.4	Route (ROUTE)	8
2.1.5	MAN OVER BOARD	8
2.1.6	TIME	8
2.2	EXTRA NEXUS FEATURES	9
3	Installation	10
3.1	Mounting the instrument	11
3.2	Installation alternatives	13
3.3	CABLE CONNECTIONS	16
4	FIRST START	17
4.1	DEFAULT SETTINGS FROM FACTORY	18
4.2	GPS STATUS and OPERATION	19
5	HOW TO USE THE 5 PUSH BUTTONS	20
5.1	PAGE BUTTON	20
5.2	LIGHT CONTROL	20
5.3	MINUS BUTTON	20
5.4	PLUS BUTTON	20
5.5	SET BUTTON	20
5.6	ACCESS TO SETTINGS	21
5.7	CLEAR (or ERASE) a WP or value	21
5.8	MAN OVER BOARD	21
5.9	ESCAPE (or ABORT) from edit mode	21
5.10	"BACK STEP"	21
5.11	GENERAL WAYPOINT SEARCH	21
6	NAVIGATION FUNCTIONS	23
6.1	POS	24
6.1.1	POSITION and ALTITUDE	24
6.1.2	DATE and TIME	24
6.1.3	BATTERY VOLTAGE	25
6.1.4	SATELLITE STATUS and SIGNAL to NOISE	25
6.2	WP	26
6.2.1	MARK WP	26
6.2.2	EDIT WP	26
6.2.3	COPY WP	27
6.2.4	MOVE WP	28
6.2.5	DELETE	28
6.2.6	ED B/R	28
6.3	NAV	29
6.3.1	COMBI VIEW and X-TRACK ERROR	29
6.3.2	ETA and TTG	29
6.3.3	DRIFT	29
6.3.4	WCV and CTS	30
6.3.5	GOTO WP	31
6.4	ROUTE	32
6.4.1	SAIL PLAN	32
6.4.2	ROUTE CALL	35
6.4.3	REVERSE CALL	36
6.4.4	DELETE	36

6.4.5	ROUTE STORE	36
7	SETTINGS	38
7.1	UNITS.....	38
7.2	ALARMS.....	39
7.2.1	Arrival line ON/OFF.....	39
7.2.2	Auto change	39
7.2.3	X-track error limit	39
7.2.4	start time.....	39
7.3	GPS Settings.....	40
7.3.1	Dampening of SOG, COG.....	40
7.3.2	latitude correction	40
7.3.3	longitude correction	40
7.3.4	Altitude correction	40
7.3.5	Set Time.....	40
7.3.6	Init position	40
7.4	DGPS	41
7.5	NMEA.....	41
7.5.1	Select NMEA output	41
7.6	OPTIONS	42
7.6.1	MAGNETIC VARIATION.....	42
7.6.2	Push button beep	42
7.6.3	WP-BANK.....	42
7.6.4	Chart Page	43
7.7	CONFIG	44
7.7.1	CHOICE OF POSITION SOURCE	45
7.7.2	STANDARD NX2 NAVIGATION SETUP	45
7.7.3	NX2 REPEATER SETUP	45
7.7.4	NMEA REPEATER SETUP.....	45
8	NMEA DATA	46
9	SPECIAL NMEA AND NEXUS APPLICATIONS.....	49
10	FAULT FINDING	53
11	TECHNICAL DATA	54
12	MAINTENANCE	55
13	WARRANTY	55
14	ABBREVIATIONS	56
15	Specifications	57
15.1	Technical specifications	57
15.2	Nexus Network introduction and user policy	57
16	Optional Accessories	58
17	Abbreviations	60
18	Warranty.....	61

1 Part specifications

NX2 GPS Navigator is delivered with all parts for mounting. Check prior to installation.

Wind Data instrument

<u>Qty.</u>	<u>Description</u>	<u>Reference</u>
1	Instrument, NX2 GPS Navigator	1
1	Instrument front cover	2
1	Drill template	3
1	Installation and user manual	4
1	Warranty card	5
2	Pin bolts for instrument mounting	6
2	Nuts for instrument mounting	6
1	Tube of silicon grease	6
1	Connection cover	6
2	4-pol screw terminal	6
1	Instrument Cable 8m	7
1	Power cable, red and black, 3 m (9 ft)	8
5	Extra wire protectors, 0,25 mm (1/100")	9
5	Extra wire protectors, 0,75 mm (1/32")	9

Additional in GPS Navigator complete with GPS Antenna

1	GPS Antenna	10
3	Mounting screws for Antenna	11

Registering of this product

Once you have checked that you have all the listed parts, please take time to fill in the warranty document and return it to your national distributor.

By returning this document, it will assist your distributor to give you prompt and expert attention, in the event of your experiencing difficulties with this product. Keep your proof of purchase. Also, your details are added to our customer database so that you automatically receive new product catalogues as and when they are released.

2 INTRODUCTION

THANK YOU FOR CHOOSING THE NX2 GPS NAVIGATOR.

The GPS system is operated by the DOD (Department Of Defence) USA and the Systems accuracy and maintenance is totally within their responsibility. Remember that a GPS navigator is a "tool" or a navaid to common navigation methods, and should therefore be used as a complement to maps and compass, and not as a replacement.

Please read about the GPS system in the NX2 GPS Antenna manual.

The NX2 GPS navigator system.

The NEXUS GPS NAVIGATOR offers TRUE multiple nav-station operation. When operating, ONLY ONE WP database is in use for the whole NEXUS system. Therefore, you may store or delete waypoints, create or call up a route on any NEXUS GPS or Multi Center instruments.

By adding this GPS navigator into the NEXUS series of instruments, you will benefit from the high integration level that makes navigation simple, precise and reliable.

2.1 Basic Features

2.1.1 Position (POS)

Position is given in latitude and longitude to 3 decimal places with selectable set-up for minutes and seconds or minutes and 1 000ths of minute. Altitude in METRES or FEET can also be displayed.

2.1.2 Navigation (NAV)

Course and Speed Over Ground (COG/SOG) in knots, km/h or miles/h. Select either magnetic or true, for both course over ground and bearing to waypoints. This will be clearly "flagged" with the reversed text MAGNETIC on the LCD to prevent confusion and uncertainty. Distance to WP is selectable in nautical miles, kilometres or miles. Actual X-track error is displayed to 3 decimal places which is perfect for high precision Differential GPS navigation.

2.1.3 Waypoint (WP)

Store up to maximum 399 WP in lat/long each with a 7 character name. You may Copy, Move or Delete a single WP or in a block.

2.1.4 Route (ROUTE)

Up to 25 "named" routes can be stored with 24 WP in each route. They can also be called and used "reversed" (e.g. return to harbour).

2.1.5 MAN OVER BOARD

For your safety, the M.O.B. (Man over board) function can be activated very easily. Please see chapter 5.8.

2.1.6 TIME

Month, day and time is displayed (local time can be set). When navigating towards a waypoint, both ETA (estimated time of arrival) and TTG (estimated time in hours and minutes to go) is displayed.

2.2 EXTRA NEXUS FEATURES

- For sailracing (with a complete NEXUS System), the built in race timer clock become extra valuable. The exact GPS time is used to "trigger" the NEXUS instruments start timer up to 1 8h and down to the last second (hh:mm:ss) before the actual start.
- With the PC-interface and software, you may transmit receive waypoints; log selected data to a file; monitor NEXUS information in real time, using a PC.

GOOD LUCK AND HAPPY SAILING!

3 Installation

You can install the NX2 GPS Navigator in two different ways:

- The GPS antenna connected directly to the NX2 GPS Navigator instrument
- The installation may also include a NX2 Server where all transducers may be connected. All data including power will pass along one cable.

- **The installation includes 6 major steps:**

1. Read the installation and operation manual.
2. Plan where to install the transducers and instruments.
3. Run the cables.
4. Install the transducers and instruments.
5. Take a break and admire your installation.
6. Learn the functions and calibrate your system.

Before you begin drilling ... think about how you can make the installation as neat and simple as your boat will allow. Plan where to position the transducers, Server and instruments. Think about leaving space for additional instruments in the future.

- **A few "do nots" you should consider:**

- Do not cut the cables too short. Allow extra cable length at the Server so it can be disconnected for inspection without having to disconnect all attached cables.
- Do not place sealant behind the display. The instrument gasket eliminates the need for sealant.
- Do not run cables in the bilge, where water can appear.
- Do not run cables close to fluorescent light sources, engine or radio transmitting equipment to avoid electrical disturbances.
- Do not rush, take your time. A neat installation is easy to do.



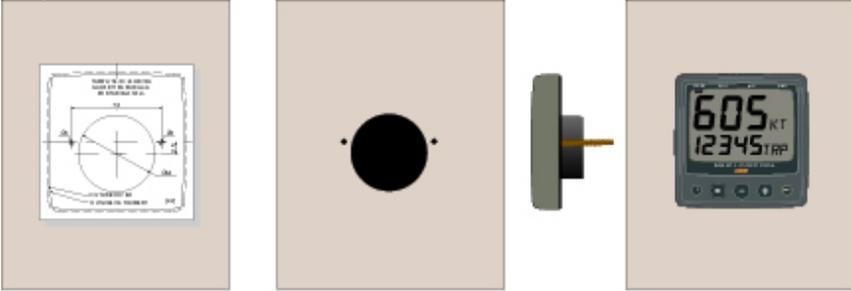
- **The following material is needed:**

Wire cutters and strippers.
 Small and large Philips and small flat head screw driver.
 Hole saw for the instrument clearance hole 63 mm (2½").
 5 mm (¼") drill for the mounting holes.
 Plastic cable ties

If you are doubtful about the installation, obtain the services of an experienced technician.

3.1 Mounting the instrument

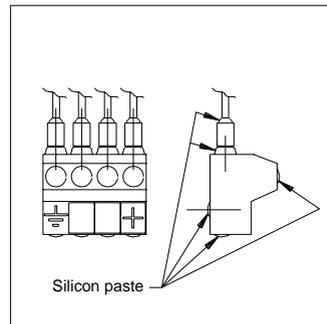
- Place the adhesive drill template on the desired location for the instrument. Drill the 2 holes using a 5 mm ($1/4$ ") drill for the two pin bolts. Use a 63 mm ($2\frac{1}{2}$ ") hole saw to machine the clearance hole for the instrument connection socket. Remove the template.



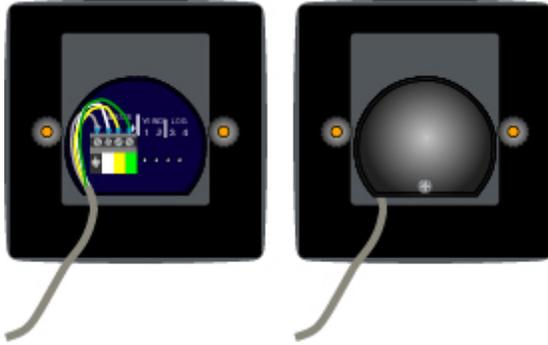
- Screw the two pinbolts to the instrument
- Put the instrument in place
- Screw the two nuts from the back

Note! The two nuts must just be tighten by hand

- Run the Nexus Network cable from the Server to the instrument.
- If you want to cut the Nexus Network cable to length, disconnect 4-pole jack plug and cut the cable. Peel off about 35 mm (1,4") of the cable insulation. Remove about 6 mm ($1/4$ ") from the 3 isolated wires (the 4th wire is an earth / screen). Attach the 4 cable protectors to the wires using a pair of flat pliers.
- Connect the 4 cable protectors to the 4-pole jack plug as shown. Apply silicon paste on all locations as shown.



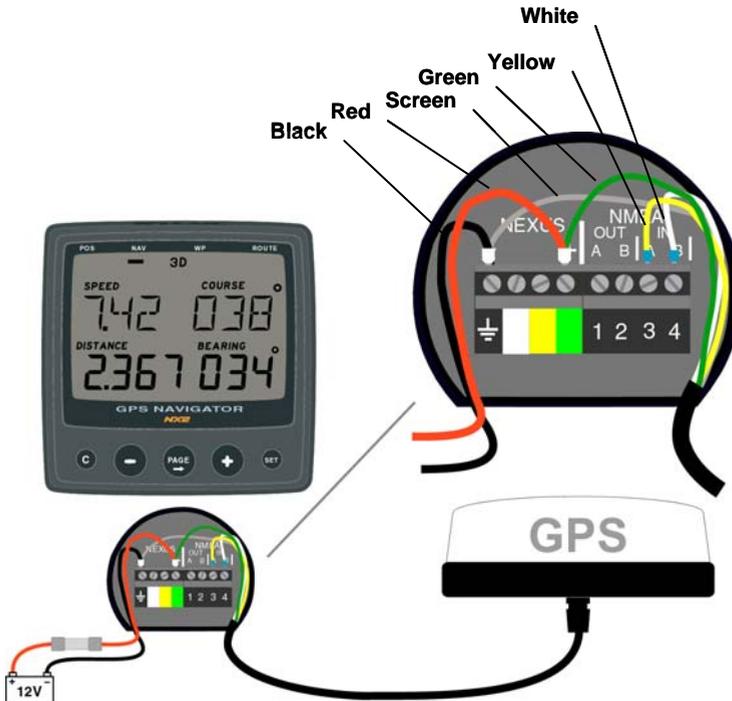
Note: Must be done to avoid corrosion.



- Apply silicon paste to the instrument connection pins at the back of the instrument. Press the jack plug onto the instrument pins. Press the cable in to the cable leads.
- Mount the connection back cover with the screw.

3.2 Installation alternatives

A. COMPLETE STANDALONE NX2 GPS NAVIGATOR INSTALLATION
 The NX2 GPS Navigator may be used stand alone without a Nexus Network. Connect the NX2 GPS Antenna or other NMEA GPS direct to the instrument. Power is also connected according to figure below.



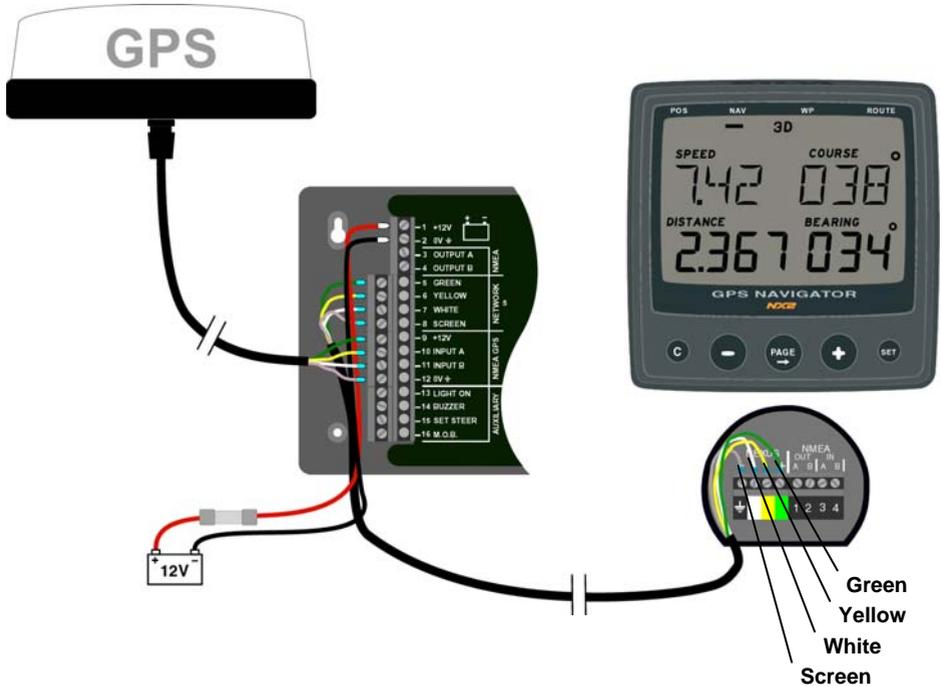
In this configuration, the instrument has to be set up as follows:

NMEA POS see 7.7

MASTER see 7.7

B. IN A NEXUS NETWORK

The NX2 GPS Navigator may be used in a Nexus Network. Connect the NX2 GPS Antenna or other NMEA GPS direct to the Server. Connect the Nexus Network cable to the instrument. Power will be supplied via the Nexus Network Cable



In this configuration, the instrument has to be set up as follows:

NEXUS POS see 7.7

MASTER see 7.7

C. AS A REPEATER IN A NEXUS NETWORK

If you already have a NX2 GPS Navigator or another GPS in the Nexus Network that is Navigating (storing the waypoints and calculates Bearing and Distance to WP etc.) you may use an other NX2 GPS Navigator as a repeater.



In this configuration, the instrument has to be set up as follows:

NEXUS POS see 7.7

REPEATER see 7.7

3.3 CABLE CONNECTIONS

The 3 m red and black power cables connect 12 V supply, ALWAYS USE WITH 3A FUSE.

Cable wiring on the instruments backside.

NEXUS databus and power.	+12V	GREEN
	DATA	YELLOW
	DATA	WHITE
	GROUND	SCREEN

NMEA 0183 output A.	TERMINAL 1
(RS 422) output B.	TERMINAL 2
NMEA 0183 input.	TERMINAL 3
(Opto)return	TERMINAL 4

4 FIRST START

After installation and before switching the power on, make sure that the GPS Antenna is away from anything that may obscure the satellites.

The instrument will then ask you to press the **SET** button to be able to give the instrument an ID or a "logical" NEXUS number.

You will then see the software VERSION and its ID number (Your instruments version number may differ from this example).



If the instruments are accessed in random order, you may reset the ID numbers for all NEXUS instruments and then start again by pressing **SET** in preferred number (remote access) order. Just press Clear during the time when VER ID is displayed. Then press the **SET** in preferred number order (always wait for the OK text before pressing the **SET** on the next instrument).

4.1 DEFAULT SETTINGS FROM FACTORY

UNITS are set to Nautical Mile for distance, Knots for speed and Metres for altitude.

POSITION presentation is set to present position in degrees minutes and $1/1000$ of a minute. Alternative is degrees minutes and seconds.

TRUE bearing and course over ground. **MAGNETIC** course can be set as an alternative. Local magnetic variation must then be set.

CONFIGuration is set for this instrument and the NX2 GPS Antenna. For repeaters or other combinations, please see settings in chapter 7.7.

4.2 GPS STATUS and OPERATION

None of the 2D or 3D flag will be lit during satellite search before navigation can start. When the GPS is tracking satellites, the status symbols 2D or 3D will be displayed at the top of the LCD, as online information. If a DGPS receiver is connected and working correctly, the symbol text DGPS will also be displayed.

When 3 satellites have been found and tracked, the 2D symbol is displayed; 3D when more than 3 satellites are tracked.

No Symbol	Acquisition of data from satellites.
2D	2 dimensional position (with locked altitude) for marine navigation.
3D	3 dimensional position for all land navigation.
DGPS	differential GPS is active.

The initial GPS receiver start is called a COLD START and will be performed if the GPS has been moved a large distance, or if used for the first time. It will take about 3 minutes and is indicated by neither of the 2D or 3D flag is on.

Warm start takes from 35 seconds up to 2 minutes depending on the age of the ephemeris almanac and your position (within 4 hours).



5 HOW TO USE THE 5 PUSH BUTTONS

5.1 PAGE BUTTON

Is used for selecting main function. Each press on this key will change to a new main function (from left to right). The selected main function will be indicated with the LCD arrow.

When editing any value, this key will also move cursor key to edit numbers or text characters with the same functions as above.



5.2 LIGHT CONTROL

Is accessed with a long press (> 2 secs) on the **PAGE** button. Three light levels, LOW, MED, MAX plus light OFF can be selected.



5.3 MINUS BUTTON

Is used to "pull down" next function from the selected main menu. When in edit mode, this button is used to increase a digit value or a text character.



5.4 PLUS BUTTON

Is used to "pull up" previous function from the selected main menu. When in edit mode, this button is used to decrease a digit value or a text character.



5.5 SET BUTTON

This is the **SET KEY** that will "unlock" a value, text or function to be set or altered, then "lock" when ready.

It is also used as a toggle page when a secondary function is available, e.g. to toggle between the Combi function and X-track error.



5.6 ACCESS TO SETTINGS

Press minimum 2 secs. on the **SET** button.



5.7 CLEAR (or ERASE) a WP or value.



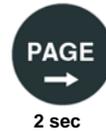
5.8 MAN OVER BOARD

To engage Man Over Board, press the two outer keys.



5.9 ESCAPE (or ABORT) from edit mode.

Press the Cursor key (**PAGE**) for minimum 2 seconds.



5.10 "BACK STEP"

Press the **PAGE** and **MINUS** simultaneously to "back step" to previous function or for moving the cursor to the left.

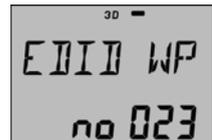


5.11 GENERAL WAYPOINT SEARCH

The SEARCH METHOD is the same for all searches. You will use it when searching for "NAMED" waypoints to edit, when activating a WP to navigate towards, or calling up a "NAMED" route, The same method is also used when selecting a "NAMED" geodetic datum.

1. Search for a waypoint number by scrolling **PLUS** or **MINUS** (increase or decrease the waypoint numbers). As an example, function EDIT WP is chosen.

To find e.g. WP "BUOY", select EDIT WP and press **SET** (No:023 shows the next free waypoint)



The display shows FREE no:023. Digits flashing, press **MINUS** to scroll backwards to find the waypoints that you have stored earlier under WP function.



The display shows ex. "BUOY" no:022. This is the last stored waypoint.



Scroll **MINUS** for other waypoints to EDIT or **PLUS** to create a new waypoint from a FREE number. Press **SET** and proceed with the editing. See chapter 6.2.2. regarding editing of WP's.

2. Search in "ALPHABETICAL" order by scrolling **PLUS** or 'DOWN'.

This example is demonstrating alphabetical scrolling in the GOTO WP function.

Select GOTO WP and press **SET**



The display shows ex. "NAME" no:023 as last edited waypoint (digits flashing).



Press the **PAGE** (cursor) button once and the "NAME" starts to flash. Use **PLUS** or **MINUS** button to scroll through all waypoints in "ALPHABETICAL" order.

3. Single character search, starting with the left hand character.

Press the **PAGE** (cursor) button once more and the first "character" in the "NAME" will flash.

By pressing the **PLUS** character in alphabetic is found in the memory

button you will display the next order and the FIRST waypoint that with that character is shown.

By pressing the **MINUS** button, you will display the previous character in alphabetical order and the LAST waypoint that is found in the memory with that character is shown.

4. Finding a WP by entering the WP number.

If we use the same example as before, there are two ways of moving the cursor to the three digit position (no:nnn).

A. Repeated press on the **PAGE** button until the left hand digit is flashing.

B. Press both **PAGE** and **MINUS** buttons to backstop the cursor.



When the desired digit is flashing, enter the number with the **PLUS** or **MINUS** button and then move the cursor to the next digit. Press **SET** lock.

6 NAVIGATION FUNCTIONS

The definition of navigation is to know where you are, where to go, and how to get there.

You may simply utilise POSition data to navigate or fully utilise the waypoint features, after the following steps.

Prepare for WAYPOINT NAVIGATION.

1. LOCATE on your chart, the LAT and LON position of your waypoint's.
2. STORE the WP's in the WP bank.
- 3, SELECT one of the WP's stored in the GOTO WP function. Prepare for SAIL PLAN NAVIGATION.
4. ADD ON additional WP's in the SAIL PLAN queue. The first WP in that queue is already selected in the GOTO WP function (point 3 above).
5. SAVE the complete SAIL PLAN as a ROUTE for later use.

A SAIL PLAN is a list of pointers (up to 24) to your pre programmed waypoints in the navigator memory. The navigator will then navigate towards the waypoints, in a sequence, one by one. You may also store the complete SAIL PLAN as a ROUTE (up to 25 routes).

When a ROUTE is called up, it will be added to the SAIL PLAN.

6.1 POS

Access levels and summary of the POS functions.

- "FIRST SHOWN" POSITION and ALTITUDE, ch. 6.1.1.
- "Press DOWN" DATE and TIME (local or UTC), ch.6.1 .2.
- "Press DOWN" BATTERY VOLTAGE (inside the instrument), ch. 6.1.3.
- "Press DOWN" SATELLITE STATUS and SIGNAL to NOISE, ch. 6.1.4.

*Tip !, Use the **PLUS** button to get access to the last function.*

6.1.1 POSITION and ALTITUDE

Latitude (top) and **longitude** (bottom) in selected geodetical datum.

Press **MINUS** to display the ALTITUDE above sea level.



6.1.2 DATE and TIME

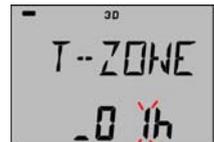
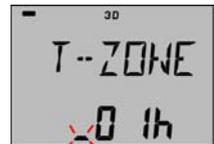
Press **SET** to set Local time zone. Add or subtract one or more hours to UTC (GMT) (GPS) time to make local time. Find out your time zone with help of the time zone map on page 2.

Note! The unit will not accept 1/2 hour time differences.

Plus indication, "_" will flash, use **PLUS** to change to minus sign, "-". Use plus indication when situated east of Greenwich and minus sign, west of Greenwich.

Move cursor with **PAGE** button to set hour difference. Increase/decrease flashing value by pressing **PLUS** or **MINUS**.

Lock the required value by pressing **SET**



6.1.3 BATTERY VOLTAGE

The battery voltage is measured inside the instrument and will differ from the NEXUS Multi Control instrument, where the battery voltage is measured in the Server.



6.1.4 SATELLITE STATUS and SIGNAL to NOISE.

HDOP (Horizontal Dilution Of Precision) has normally a low value. If higher than or equal to 1.0, the 2D or 3D will start to flash as a warning of bad satellite geometry

Note Not with NX2 GPS Antenna



4 SAT indicates the number of satellites used min 3 and max 15. The GPS will internally track up to 12 satellites.

6.2 WP

Note! This page is only accessible when the NX2 GPS Navigator is in MASTER or SLAVE mode. Not accessible when operating as a REPEATER. See 7.7.

Access levels and summary of the WP functions

- "FIRST SHOWN" MARK WP (Marks a waypoint from pre sent position), chapter 6.2.1.
- "Press **MINUS**" EDIT WP (EDIT a WP in Lat/Lon), chapter 6.2.2.
- "Press **MINUS** " COPY WP (Copy one or a block of WP's to another memory part), chapter 6.2.3.
- "Press **MINUS** " MOVE WP (As with COPY but clears the "from" memory when done), chapter 6.2.4.
- "Press **MINUS** " DELETE (DELETES one or a block of WP's), chapter 6.2.5.
- "Press **MINUS** " ED B/R (EDIT a WP in Bearing and range), chapter 6.2.6.

Note! All waypoints are stored and identified with an unique number and with any 7 alphanumeric "NAME".



6.2.1 MARK WP

Use MARK WP when passing a position to store for later use. The position will be stored directly when the **SET** is pressed.

The first free waypoint is shown in the example as no 002.

Press **SET** and you are invited to optionally give the waypoint a name. Enter the character with **PLUS** or **MINUS** buttons and move to the next character with the **PAGE** button (cursor). Press **SET** when ready.

Next free WP to MARK will now be ready.



6.2.2 EDIT WP

EDIT WP (In latitude/longitude)
Use EDIT WP when creating a new WP or when editing an old WP.



Press **SET** and the text FREE is displayed with the WP number flashing. Accept this free WP by pressing the **SET**.



*Note! When editing an "old" WP you may search for it by scrolling through the numbers with **PLUS** or **MINUS** button. You may also use the **GENERAL WAYPOINT SEARCH**, see ch 5.11.*

Give your WP a name (optional) and follow the same routine as described in chapter 6.2.1, then press **SET**.

Now, the position is shown in latitude and longitude Enter the correct latitude with **PLUS / MINUS** and **PAGE** (cursor) and press **SET** Enter correct longitude in the same way and press **SET**



Note! Make sure you set the correct hemisphere for lat (N/S) and long (E/W).

DELETE a WP

You may also delete a WP and make it a FREE position by **CLEAR**

WARNING!

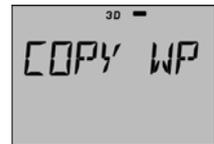
If you have created a ROUTE and then later change or delete a WP that is within that ROUTE, the ROUTE will be affected

Our recommendation is to decide early how to organise the waypoints You may use the first 1 GO WP for "temporary" waypoints and the rest as more "permanent" WP's for use in ROUTES Always check that the GPS datum and the chart datum match



6.2.3 COPY WP

Copy one or a block of WP's to another position without erasing the original block of waypoints



Press **SET**



Press **SET** (first digit flashing)

Select the FIRST WP (12) in the "block" and press **SET** Select the LAST WP (200) in the "block" and press **SET**



Select the TO WP number for the WP block 012-123 Set this WP for example "address" to 200 and press **SET**



DONE!

6.2.4 MOVE WP

MOVE WP

Is the same as COPY with the difference that it will first copy the selected WP's to the new block position before the original waypoints will be erased.



6.2.5 DELETE

Deletes a single or a block of WP's by use of the same procedure as in COPY and MOVE.



Warning ! There is no way back if DELETE is fully executed. But if you accidentally press the **SET**, you may ESCAPE without DELETING with a long press on the **PAGE** button.



6.2.6 ED B/R

ED B/R (EDIT a WP in Bearing and range from present position).



Note! BEARING and RANGE is ALWAYS in TRUE NORTH from PRESENT POSITION.



Press **SET** and FREE is displayed, accept or select an other free WP number and press **SET**.
Enter the WP's "NAME" (as described iii chapter 6.2.1) and press **SET**.



"WP NAME"(example shows distance 1 2.24 NM and bearing 205 from 1 2.34 205 present position)



6.3 NAV

Access levels and summary of the NAV functions

- "FIRST SHOWN" COMBI VIEW and X-TRACK ERROR, chapter 6.3.1
- "Press **MINUS**" ETA and TTG (Arrival time or time to go to WP), chapter 6.3.2
- "Press **MINUS** " DRIFT (Tidal and boat drift), chapter 6.3.4.
- "Press **MINUS** " WCV (VMG to WP) and CTS (Course To Steer including Drift), chapter 6.3.5.
- "Press **MINUS** " XTE (Cross track error)

6.3.1 COMBI VIEW and X-TRACK ERROR

The most used function in NAV is the COMBI VIEW where you will see;

SPEED and COURSE OVER GROUND, DISTANCE and BEARING TO WAYPOINT (When a WP is active)

The X-track error is the distance of 90° from your track. The symbol Δ indicates that the error is to the left, or right, of your track.

Note! To make COG (Course Over Ground) stable, use higher dampening at low speeds and lower dampening at high speeds. Try to keep dampening as low as possible. Row to set dampening, see chapter 7.4.



6.3.2 ETA and TTG

Estimated Time of Arrival

Note! ETA is calculated on the assumption that both speed and direction will be constant during travel towards the waypoint.

Press **MINUS**

TTG or Time To Go in hours and minutes to the WP with the same criteria as ETA.



6.3.3 DRIFT

When both Compass heading and log data are available, the boats drift including tide (speed and direction) can be calculated. In the



example, the boat is drifting on a bearing 234~ with the speed 0,8 knots.

Press **SET** to set the damping of SET/DRIFT and CTS (please see below).

Note! The dampening setting will affect all instruments and is not local, as with boat speed and compass.

The damping will correspond to the following;

D0 = 5s	d1 = 10s	d2 = 20s
D3 = 40s	d4 = 1 min 20s	d5 = 2 min 40s
D6 = 5min	d7 = 10min	d8 = 20min
D9 = 40min		

6.3.4 WCV and CTS

WCV (Waypoint Closing Velocity) is the speed made good towards the waypoint. CTS (Course To Steer) is the course (selectable TRUE or MAGNETIC) that the boat must keep to be able to reach that waypoint in a straight line. CTS includes compensation for the boats drift.

See DRIFT chapter 6.3.4.

Note! CTS does not include the calculation for changes in tidal direction.

6.3.5 GOTO WP

The GOTO WP function is the fastest way of selecting a WP to go to and it is normally accessed by pressing the **SET** button once wherever you are in the NAV page except in DRIFT (where **SET** sets the dampening) in the Nav function.



Press **PLUS** or **MINUS** to select the waypoint you want to go to. Press the **SET** again to select your WP to GOTO, in this example, "BOUY NE" was the last edited WP.



Last edited WP is displayed
Digits "flashing", (you may select another WP)

Press the **SET** to accept this WP and the navigation will start

WP 000 is defined as the "present position" and is used as the FROM waypoint and WP 134 "BOUY NE" is the TARGET waypoint
4
1



How to use GOTO WP in combination with the SAIL PLAN

The GOTO WP function is actually a direct jump to the SAIL PLAN's first LEG (the "active" WP), then replacing that WP with a new "GOTO WP" waypoint

Example; You have set up a SAIL PLAN with 1 2 WP's and on the first LEG you are navigating towards is WP134 "BOUY NE", then by some reason you decide to go to WP104 "BOUY NW" instead

To make this easy, start from the Combi Nav display and press **SET** to the GOTO WP function, select WP1 04 "BOUY NW", then press **SET** again (navigation starts)

Press **MINUS** to return to the Combi Nav display where you will see your new Distance and Bearing to "BOUY NW"

Note! The "old" PROM WP will be replaced with "present position" to begin a new X-N-ack error calculation. When the Arrival alarm criteria appears, next WP in the SAIL PLAN is activated as normal.



6.4 ROUTE

Note! This page is only accessible when the NX2 GPS Navigator is in MASTER or SLAVE mode. Not accessible when operating as a REPEATER. See 7.7.

Access levels and summary of the ROUTE functions

"FIRST SHOWN"	SAIL PLAN (Create, or edit the sail plan), chapter 6.4.1
"Press DOWN"	ROUTE CALL (Call a route for use), chapter 6.4.2
"Press DOWN"	REVERSE CALL (Call a route for use in the opposite direction), chapter 6.4.3.
"Press DOWN"	DELETE (Delete a route), chapter 6.4.4.
"Press DOWN"	ROUTE STORE (Store the complete sail plan as a route), chapter 6.4.5.

6.4.1 SAIL PLAN

The **SAIL PLAN** is the "tool" where you can create, delete or insert one or more WP's to form a number of LEG's. The complete SAIL PLAN can then be stored and named in ROUTE STORE. Up to 24 WP's can be used in plan (Each ROUTE can then consist of maximum function each sail 24 WP's).

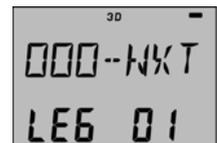


NOTE! A route is a stored Sail Plan. The Sail Plan is the current list of waypoint to go to and when you pass a waypoint, it will disappear from the Sail Plan list. (However, the waypoint is still in memory)

How to make the first LEG:

Press **SET** in SAIL PLAN

WP 000 is defined as present "START" position. NXT (Next) indicates that the next WP is ready to be selected to form the first LEG.

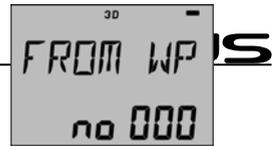


Note! You may choose any other waypoint as the "START" WP.

Press the **MINUS** button.



To select another FROM WP, press the **SET** and select your start WP. The primary effect is that the X-track error will be calculated by use of the new FROM WP and the TARGET WP, see drawing



Normally, WP 000 (current position/present position) is accepted as the "START" WP.

Press the **PLUS** button (LEG 01) and press **SET**.

The last edited WP is displayed flashing. Use the GENERAL WAYPOINT SEARCH, chapter 5.11 for finding the first WP to go to and press **SET**.



As an Example we choose "BOUY SW" and then press **SET**.

Note! Before distance and bearing to the target WP is displayed, the LEG number is shown.

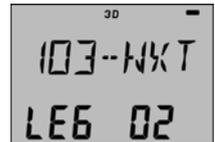


The distance to "BOUY SW" is 32.34 NM and the bearing is 2340 in this first LEG.



Press the **PLUS** button for NEXT LEG;

WP 103 will be the FROM WP for the NEXT LEG (LEG 2).



Press **SET**, get next WP and press **SET**.



Repeat until a maximum of 24 WP's (LEG's) have been included in the SAIL PLAN.



Also, make it a habit to always VERIFY the Distance and Bearing for all LEG's in the SAIL PLAN, especially if stored as a ROUTE



Important! You will affect the ROUTE if you change the lat/ long position for a waypoint that is used within that route.

CLEAR SAIL PLAN.

To clear the complete SAIL PLAN, press **CLEAR**, **PLUS** and **MINUS** buttons simultaneously when the text SAIL PLAN is displayed. The display will then show CLEAR PLAN for a short moment.

INSERT A LEG INTO THE SAIL PLAN.

EXAMPLE. Insert a new leg (WP 1 27) between the present WP 103 and WP 107. This will move WP 107 one LEG minus in the SAIL PLAN queue list. Use the **PLUS** and **MINUS** buttons for scrolling through the different LEG's in the SAIL PLAN.

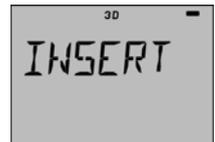


LEG 02 is first displayed, then distance and bearing;

BEFORE, WP 103 ----- LEG 2 ----- WP 107

INSERT of a new LEG by pressing both **PLUS** and **SET** buttons simultaneously at the preferred "LEG INSERT" location.

The text INSERT appears followed by the normal "search" window where you select WP 127.



AFTER THE INSERT, WP 103 ----- LEG 2 ----- WP 127
 ----- LEG 3 ----- WP 107

DELETE A LEG

Example; Delete WP 1 27 in LEG 2 without any other effect in the SAIL PLAN Use **PLUS** and **MINUS** buttons for scrolling through the different LEG's

LEG 2 is first displayed, then distance and bearing;



DELETE WP 1 27 in this LEG by pressing both **PLUS** and **MINUS** buttons simultaneously at the preferred "LEG" location (LEG 02)

BEFORE, WP 003---LEG 2---WP 127---WP024

AFTER, WP 003---LEG 2---WP 024

6.4.2 ROUTE CALL

At least one ROUTE must have been stored to be able to use this function

This function will ADD a selected ROUTE to the SAIL PLAN in the same way as it was created It is therefore possible to ADD ON (or "link") a new ROUTE into the SAIL PLAN as long as the number of WP's are less then 25



Tip! It is practical to ADD ON a new ROUTE when only 2 or 3 WP's are remaining in the SAIL PLAN, thus creating a long "seamless" ROUTE

WARNING!!

If you have created a ROUTE and then later change or delete a WP within that ROUTE, it will be affected



Press **SET**

"012 flashing", select your ROUTE and press **SET**

The ROUTE is now ADDED to the SAIL PLAN and you will see the LEG number briefly, then Distance and Bearing between "FROM" and "TO" will be displayed



Note! If you are ADDING the ROUTE to another ROUTE, you will get into the SAIL PLAN's actual LEG number for this Route's first WP



6.4.3 REVERSE CALL

At least one ROUTE must have been stored to be able to use this function.

The selected ROUTE will be copied to the SAIL PLAN in reverse order. It is ADDED to the SAIL PLAN as in the ROUTE CALL.

Press **SET**, "012 flashing"

Select your ROUTE and press **SET** (it will now be your REVERSE ROUTE).

See also ROUTE CALL regarding ADDING Route's.



6.4.4 DELETE

Delete a selected ROUTE in memory.

Press **SET**

Select the ROUTE which shall be deleted and press **SET**

Warning! There is no way back if DELETE is executed.



6.4.5 ROUTE STORE

Store the SAIL PLAN as a ROUTE (in chapter 6.4~1)

Press **SET**, "001 flashing"



The first free ROUTE is no 001, press **SET** and give the route a name by using the **PLUS**, **MINUS** and **PAGE** buttons

Press **SET** and the number of stored WP's are displayed



7 SETTINGS

Enter the SETTINGS by pressing the **SET** button minimum 2 secs.



2 sec

There are seven groups of SETTINGS

- UNITS**
- ALARMS**
- GPS**
- DGPS**
- NMEA**
- OPTIONS**
- CONFIG**
- RETURN**

Scroll between the main settings with **PLUS** or **MINUS**, press the **SET** in any of the main settings to enter the submenu

Then select from the submenu with **PLUS** or **MINUS** and press **SET**.

Press **PAGE** to return back to a "higher" level or back to normal operation mode.

7.1 UNITS

- DST NM Select NM, KM or MILES
- SPD KTS Select KTS, Km/h or MPH
- ALT M Select M or FT
- SECONDS OFF Select ON when using charts with degrees, minutes and seconds (OFF = minutes and 1/1000 of a minute)



RETURN Return from UNIT set-up

7.2 ALARMS

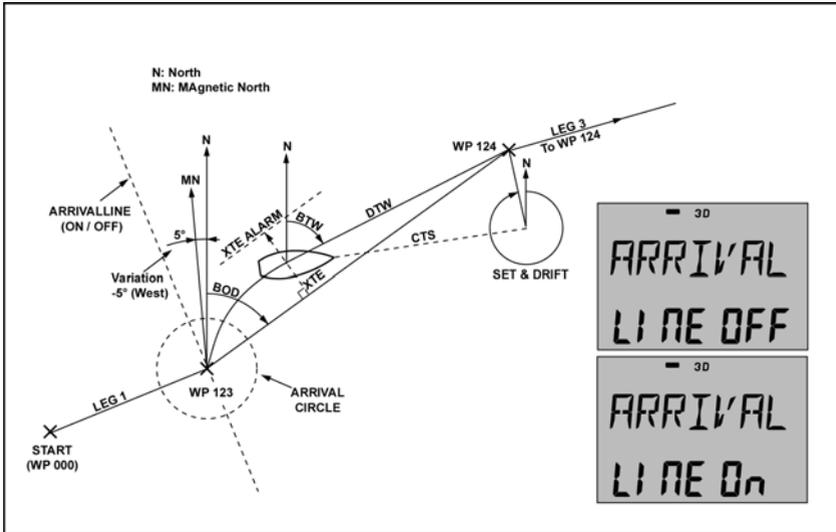
Arrival circle alarm, within the set radius.
 Ex. shows circle with 0.20 Nautical miles radius.

Note! The Circle Alarm MUST be in Nautical Mile.



7.2.1 Arrival line ON/OFF.

(see drawing:).



7.2.2 Auto change

Auto change to next WP in the sail plan. Can be important when used with autopilots.



7.2.3 X-track error limit.

Ex. shows alarm value entered, 2.5 NM.
Note! The XTE Alarm MUST be in Nautical Mile



7.2.4 start time

Set **actual start time** (within 18 hrs) to be used to trig the NX2 Multi Control start timer.

RETURN from ALARM set-up.



7.3 GPS Settings

7.3.1 Dampening of SOG, COG

The damping will correspond to the following;

d0 = 0s d1 = 1.8s d2 = 2s d3 = 10s d4 = 20s
 d5 = 40s d6 = 1'20s d7 = 2'40s d8 = 5' d9 = 10'

This dampening affects Speed Over Ground and Course Over Ground.



7.3.2 latitude correction

Note! This is only possible for older Nexus GPS Antennas that are Nexus network compatible (Art no. 21000

Manual latitude correction from WGS-84 in Nautical 0'205 Miles,
Note! Only in 1/1000ths of a minute.



7.3.3 longitude correction

Note! This is only possible for older Nexus GPS Antennas that are Nexus network compatible (Art no. 21000

Manual longitude correction from WGS-84 in Nautical 0'023 Miles, *Note! Only in 1/1000ths of a minute.*



7.3.4 Altitude correction

Note! This is only possible for older Nexus GPS Antennas that are Nexus network compatible (Art no. 21000

Altitude correction in selected unit (metres or 025feet) from WGS-84 to selected geodetic datum



7.3.5 Set Time

T-ZONE, YEAR, DATE, TIME,

Note! This is only possible for older Nexus GPS Antennas that are Nexus network compatible (Art no. 21000)

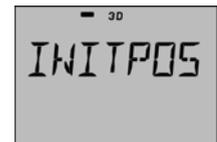


7.3.6 Init position

Note! This is only possible for older Nexus GPS Antennas that are Nexus network compatible (Art no. 21000

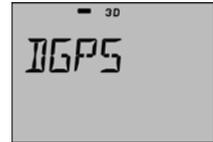
Set initial estimated position (within 100 km), speeds up the time to first FIX.

RETURN from GPS setup



7.4 DGPS

This is a special POP UP feature for future differential receivers.

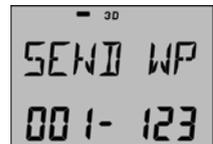


7.5 NMEA

Receive NMEA 0183 waypoints ON/OFF.



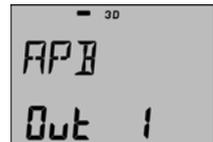
Send out internal WP's once via the NMEA port. Select an individual WP or a group of WP's.



7.5.1 Select NMEA output.

Select NMEA output for the 8 channels
Each one of the 8 channels can also be set to -, meaning, no output.

See further information in NMEA 0183 DATA



RETURN from NMEA setup.

7.6 OPTIONS

Magnetic bearing

Magnetic bearing is displayed for BTW, HDC, COG, CTS and SET. The MAGNETIC flag is then displayed.

7.6.1 MAGNETIC VARIATION.

Max 99.9 degrees. (EAST-- +, WEST--).

Note! This setting will directly by affect the compass if it is present.



7.6.2 Push button beep

Push button beep ON/OFF.



7.6.3 WP-BANK

Select for use with Multi instruments,(000, 100, 200, 300....)

Example, if you select WP bank 200 then all waypoints accessed from a Multi instrument will be in this bank (200 299). This means that when you edit waypoint no: 22 in a Multi, you are actually changing waypoint no: 222.



This is a special function for transfer (import) of WP's FROM a NEXUS MASTER GPS Navigator instrument TO a NEXUS repeater instrument,



Important! IMPORT can only be done from a NEXUS repeater instrument.

You must also select WP-BANK since IMPORT will transfer in blocks of 100 WP's. You can IMPORT another NEXUS GPS instrument.

Example 1.

Move all 99 WP's from the Server to this instrument's WP BANK 300. The Servers WP's from 1 to 99 will then be stored in memory position 301 to 399.

Do as follows,

1. Set to NEXUS REPEATER in the CONFIG
2. Switch POWER OFF then ON to activate this mode change.
3. Set the WP-BANK to 300.
4. Select IMPORT and press the **SET**
5. Set to MASTER in the CONFIG mode and switch POWER OFF and ON again.
6. You are now able to use the Servers waypoints 1 99 as WP's 300-399.

Example 2.

Move WP 100 to 200 from NEXUS GPS navigator "A" to NEXUS GPS navigator instrument "B" (into memory position).
-instrument the same

Do as follows,

1. Set to MASTER in the CONFIG for NEXUS GPS "A".
2. Set to NEXUS REPEATER in the CONFIG mode for NEXUS GPS "B".
- 3 Switch POWER OFF then ON to activate this mode change.
4. Set the WP-BANK to 300 (in "A" or "B")
5. Select IMPORT in "B" and press the **SET**.

7.6.4 Chart Page

Reserved for future POP UP use, set to OFF.

RETURN from OPTION set-up.



7.7 CONFIG

MASTER, NEXUS-REPEATER or NMEA-REPEATER.

NEXUS POS or NMEA P05.

NMEA input or RTCM input.

RETURN from CONFIG setup.



Important! Always switch POWER OFF then ON to activate a mode change.

MASTER

Primary navigation is performed in the MASTER instrument. **Only one MASTER instrument is allowed.**

NEXUS REPEATER

The MASTER instrument can be remotely controlled from this instrument. There is no difference in functions between a MASTER and a REPEATER.

NMEA REPEATER

Navigation is processed by an external NMEA navigator and then repeated here. The NMEA navigator is connected to THIS instrument, you must therefore also select NMEA P05 as the position source (see chapter 7.7.1). You can NOT use the GOTO WP or ROUTES, as long as this instrument acts as a pure NMEA repeater. The NMEA data is also converted and is sent out on the NEXUS Network.

7.7.1 CHOICE OF POSITION SOURCE

This GPS navigator instrument can as an option, use NMEA position data from a GPS receiver or from an active GPS Antenna. If NMEA POS is selected, you must connect the NMEA source to this instruments NMEA 0183 input port, on the back of the instrument, see chapter 3.3.

Note! A SILVA GPS Antenna or GPS COMPASS will automatically take over and transmit position data when connected. The NMEA POS set-up is therefore only important when a NMEA position source is to be used.

CONFIG: NMEA-POS - Standard set-up with NX2 GPS

CONFIG: NEXUS-POS - Optional set-up when instrument used as a Repeater

7.7.2 STANDARD NX2 NAVIGATION SETUP

CONFIGuration is: **MASTER** and **NMEA POS**.

This is the default CONFIGuration for the sole GPS Navigator instrument connected to the SILVA GPS Antenna.



7.7.3 NX2 REPEATER SETUP

New CONFIG: **NEXUS REPEATER** and **NEXUS POS**.

All additional GPS Navigator instruments (for multiple Nav-stations) must be set as NEXUS REPEATERS. There can be only **ONE MASTER** in the system.



7.7.4 NMEA REPEATER SETUP

New CONFIG: **NMEA REPEATER** and **NMEA POS**.

When used as a Navigation REPEATER. This set-up will enable NMEA NAVIGATION data from the external navigator or PC, then convert and REPEAT it on to the NEXUS Network.



When used as a navigator, it will take the NMEA position data from a NMEA GPS Antenna or a navigator, then use the internal waypoints and sail plans as if it was a sole GPS NAVIGATOR.

8 NMEA DATA

SILVA NMEA 0183 Input/Output

This document gives a description of the NMEA 0183 sentences sent and received by the GPS navigator instrument

HDC (Heading Comppass) and BSP (Boat speed) is also sent out on NMEA when available from the NEXUS Network.

When used as a NMEA repeater, all data will be retransmitted on to the NEXUS Network.

Note! In the CONFIG SETUP there is a choice between NMEA-0183 and , RTCM Input. If RTCM is selected the NMEA Input port is used for RTCM (DGPS) corrections only. The NMEA 0183 output will only operate normal as long as the RTCM Input is set to 4800 baud (bits/sec).

Output

The output from the GPS Navigator instrument is divided into 8 different "time-slots". The required NMEA sentence can, be selected (or de-activated) individually for each slot. The complete period for all slots is two seconds, so the time between each slot is $\frac{1}{4}$ sec.

Data that is not available will be sent with null fields.

Checksum is added on all sentences. Talker ID (address character 1 and 2) is always GP (GPS source).

The following sentences can be selected (in the SETUP in the sending Instrument):

No:	Sentence:	Contents:
0		No sentence sent
1	APB	Autopilot "B"
2	BOD	Bearing, origin to destination
3	BWC	Bearing & Distance to Waypoint
4	GLI	Geographic position
5	GGA	Global Positioning System Fix Data
6	HDT	Heading Coarse (True)
7	RMB	Minimum Navigation data
8	RMC	Minimum Specific GPSI TRANSIT data
9	VDR	Set & Drift
10	VHW	Water speed and heading
11	VTG	Track made good and ground speed
12	WCV	Waypoint Closure Velocity
13	WPL	Waypoint Location
14	XTE	Cross-Track-Error
15	ZDA	Time & Date

Examples of each sentence listed above:

```

$IIAPB,A,A,0.002,L,N,,, 1 48,T,004, 1 48,T, 151 ,T* 1 D
$IIBOD,1 48,T,145,M,004,000*24
$IIBWC,090502,591 2.888,N,01 81 2.577,E, 1 48,T, 1 45,M, 15.661 ,N,004* 1 E
$IIIGLL,5926.144,N,01 756.232,E,090502,A*3C
$IIIGGA,090502,5926. 1 44,N,01 756.232,E, 1,4,1.49,1 7,M,,,, *27
$IIHDT,027,T*39
$IIRMB,A,0.002,L,000,004,59 1 2.888,N,01 81 2.577,E, 15.660,148,0.53, * 58
$IIRMC,090503,A,5926. 1 44,N,01 756.232,E,0.64, 173,1 50295,003,E*5F
$IIVDR,226,T,224,M, 1.21 ,N,2.24,K*58
$IIVHW,028,T,025,M,0.00,N,0.00,K*58
$IIVTG,253,T,250,M,0.94,N, 1 .74,K*55
$IIWCV,0.00,N,004*0A
$IIWPL,591 2.888,N,01 81 2.577,E,004*60
$IIIXTE,A,A,0.058,L,N *44
$IIIZDA,090753,1 5,02,1 995,-01 ,*79

```

Note! The WPL (WayPoint Location) sentence, only contains the position of the destination Waypoint. All other Waypoints will be sent out when the SEND-WP function is activated in the SETUP.

Waypoint ID's are equal to the true (none banked) WP number in the NEXUS Network (with digits). There is no Waypoint Base Number as in the Server-Unit.

Input

The NMEA input in the GPS navigator instrument is exclusively used for POSITION and NAVIGATION data (including Waypoints).

The received data is divided into three categories:

- 1) Basic POSITION related data: POSITION, SOG/COG, TIME/DATE and a limited satellite status if the sender is a GPS.

This information is received and sent out on to the NEXUS Network, but ONLY IF the NMEA-POS is selected in the CONFIGuration SETUP.

- 2) NAVIGATION data: BTW, DTW, BOD, XTE plus Set and Drift

This information is received ONLY IF the NMEA-REPEATER is selected in the CONFIGuration SETUP.

The GPS instrument will automatically calculate related data that is used in the NEXUS Network, such as: Set and Drift, WCV, TTG and CTS (Coarse To Steer).

- 3) WAYPOINTS: Waypoints are received from WPL sentences if the REC-WPT is ON in the NMEA SETUP.

If the receiving GPS instrument isn't the active navigator (MASTER) the Waypoint will automatically be sent to the active navigator through the NEXUS Network.

See further in the Multi Control manual for using NMEA with the Nexus Server.

9 SPECIAL NMEA AND NEXUS APPLICATIONS

In some applications, you might need an EXTRA NMEA input port. This is possible by using the NEXUS Server (with one Multi Control instrument) together with one NEXUS GPS navigator instrument. This CONFIGuration will convert NMEA position to NEXUS Network and the NEXUS GPS Navigator instrument will do the Navigation.

Example:

A boat is equipped with a NMEA GPS Antenna (or a NMEA 0183 navigator) and a NEXUS Chartplotter (see also page 43,44 Tip! for the Chartplotter).

The active NMEA GPS Antenna is connected direct to the NEXUS Server's NMEA input port and the Chartplotter is connected to the NMEA input port and output port on the NEXUS GPS NAVIGATOR instrument.

CONFIGuration in the NEXUS GPS instrument is: **MASTER and NEXUS POS.**

The Server will then have one NMEA output port free for use with an Autopilot, radar, MAXI Repeater or any other NMEA application. On the NEXUS Network, additional transducers can be used for wind speed, wind angle, depth, log and compass heading.

NMEA INPUT

The NEXUS GPS NAVIGATOR input port (normally used as the NMEA 0183 input) can also be set to receive the RTCM 104 messages for the SILVA GPS COMPASS. It is preferable to use 4800 baud on the RTCM data to utilise the NMEA 0183 standard output data specified at this baud-rate.

Alternative RTCM, Then select baud rate, see below.



Select baud rate if RTCM is selected and then RETURN.

Note! If possible, always use 4800 baud for RTCM data, it will NOT then affect the baud rate for the NMEA output (4800 is the standard).

9.1 TOGETHER WITH NEXUS CHARTPLOTTER

The link between paper charts and electronic navigation instruments. It is used as the navigation tool that will make both WP navigation and position identification extremely simple, fast and reliable.

When the Chart plotter is used with this navigator instrument and the SILVA GPS Antenna, it is preferable to connect the Chart plotter direct to the instrument. Connect battery POWER, NMEA IN and NMEA OUT without further cabling.

See connection diagram.

Navigation tips!

Select WP 001 in the GOTO WP function on the GPS navigator and then select WP 01 the WAYPOINT mode on the Chart plotter.

Now move the "puck" to the position you want to go to and press the top left button. That position co-ordinate will then be "transferred" as WP 01. The NEXUS NAVIGATOR immediately starts navigating towards that WP, whenever a new "WP" to go to is preferred, move the puck to it and "click". This unique feature makes WP navigation very easy as there is no need for storing and recalling waypoints.

If you prefer to use the Chart plotter as the tool for fast storing of a great number of waypoints (over 100), you must first enter the Chart plotters set-up and select WP block number according to this:

0183	for WP's 00 and up to 099
0183-1	for WP's 00 and up to 099
0183-2	for WP's 00 and up to 099

When this set up is correct, the WP's will be received and stored in the corresponding NEXUS NAVIGATOR's memory.

9.2 SPECIAL USE TO GET EXTRA WP's.

When two or more navigator instruments are connected to the NEXUS Network and if more than one "skipper" or family are using the boat, it is sometimes practical to utilise two completely separate WP bank's.

This can be done by changing the CONFIG in the two instruments, giving two users 399 WP's each. This can also be done with more than two instruments (up to 32 navigator instruments !!).

Do as follows:

Dedicate the instruments between you "personal" navigators. Enter the CONFIG set up on "your partners" navigator and set it to NEXUS REPEATER

Then enter the CONFIG set-up on "your" instrument and set it to MASTER. Turn the power OFF and then ON again to activate this change. The waypoints are now used from the new MASTER instead. Both (or all) instruments can now use the "new" waypoint bank.

9.2 EXTRA FEATURES WITH SILVA NEXUS NETWORK

Integrate the navigator with the NEXUS Multi Control and Server by adding compass and speed transducers. You will then get compass heading, boat speed, drift and tidal data (its speed and direction).

PC-INTERFACE CABLE

The interface, (RS 232 to RS 485) is built-in in the 25-pole D-SUB connector which connects to the PC (use 25-9 pole adapter if necessary).

Connect the interface cable (art.no. 20913 or 21122) between PC and GPS. Select the function REMOTE, then run the interface software (see instructions).

Contact your SILVA dealer for more information.

10 FAULT FINDING

Check:

- Sufficient battery voltage.
- Cables for damage.
- Faulty contact in connectors.
- Connector corrosion caused by poor protection.
- Short circuit on the NEXUS Network.

The following error messages can appear on the display:

Some errors are made by improper connections or when calling for unconnected functions (missing transducers).

- 01 = Stack error.
- 02 = SILVA BUS missing, Check databus colours and connections.
- 03 = Watchdog Timeout, Check the connections.
- 04 = EEPROM: Read-error.
- 05 = EEPROM: Write-error.
- 06 = RAM-MEMORY Read-error
- 07 = UART Queue-Pointer-error
- 0B = Break Point Reset
- 09 = EEPROM-Initialization
- 10 = Range-error caused by incorrect format, e.g. 17070 minutes East.
- 11 = Remote command that can not be performed (calibration-error)
- 12 = No response, or missing navigator unit
- 13 = WayPoint Not DEFINed
- 14 = Operation that can not be done with external NMEA navigator.
- 15 = Operation that can not be done in AUTO-Pilot Mode
- 16 = (notused)
- 17 = (notused)
- 18 = (notused)
- 19 = (notused)
- 20 = GPS -> CPU: Communication Error.
- 21 = GPS AQUISITION - failure (time out during indoor use).
- 22 = CPU -> GPS: Communication errori
- 23 = DGPS (RTCM) overrun
- 24 = Bad-Fix (1-Fix timeout)
- 25 = (not used)
- 26 = (not used)
- 27 = Extended Object Server Error (set the GPS to Master)
- 28 = Route command error (bank, full..)

11 TECHNICAL DATA

Dimensions:	113 x 113 x 23 mm
Data cable:	8 m. Battery cable 3 m.
Battery voltage:	Mm. 6.0 V, max. 16.5 V.
Power consumption:	Without light 0,1 W, With light 0,8 W.
Temperature range:	Operation -20C to +70C. Storage -30C to + 80C.
Weight:	Instrument: 280 g

12 MAINTENANCE

Clean the instrument with mild soap solution only

- Do not use high-pressure washing equipment!
- It is advisable to remove the instrument during long cold periods.
- Put silicon grease on each contact.
- Check terminals and use wire protection.

13 WARRANTY

SILVA SWEDEN AB gives a two year warranty against manufacturing faults or faulty components. The supplied warranty card together with a purchasing receipt must be shown if a warranty claim is made. The warranty does not apply to damage caused by careless handling or faulty installation. The warranty does not apply to secondary damage caused by faults in instruments or transducers. The right to change the specification is reserved by the manufacturer.

SILVA SWEDEN AB reserves the right to change product specifications without notice.

14 ABBREVIATIONS

2D	2-dimensional navigation
3D	3-dimensional navigation
ALT	Altitude
AQU	Acquisition
BOD	Bearing origin destination (the FROM WP)
BRG	Bearing
BTW	Bearing To Waypoint
COG	Course Over Ground
COR	Correction of LATILON from WG584
CTS	Course To Steer
DGPS	Differential GPS
DoD	Department of Defence
DTW	Distance To Waypoint
EDIT	Programme /enter or alter a value or a name
ETA	Estimated Time of Arrival
F	Figure of merit
GPS	Global Positioning System
HDOP	Horizontal Dilution of Precision
INIT P05	Initialisation of a known position in cold start
MAG VAR	Magnetic Variation
MOB	Man Over Board
NAV	Navigate
NMEA	National Marine Electronic Ass.
POS	Position
RTCM	Differential Correction Standard
SAT	Satellites used in navigation.
UG	Time to go to next WP.
VMG	Velocity Made Good
WCV	Waypoint Closure Velocity
WP	Waypoint
XTE	X-Track Error

15 Specifications

15.1 Technical specifications

Dimensions:	Wind Data instrument: 110 x 110 mm. (4.3x4.3 inch)
Instrument cable:	
Power sPLUSply:	12 V DC (10-16 V). The instrument is polarity protected.
Power consumption Instrument:	0,08 W 0.8 W (at max illumination)
Log- and temp sensor:	12 mW
Wind transducer:	50 mW
Temperature range:	Storage: From -30°C to +80°C. (-22°F to 176°F) Operation: From -10°C to +70°C. (14°F to 158°F)
Weight:	Instrument: 283 g (9.98 oz). Transducer: 293 g (10.33 oz).
Enclosure:	Instrument. Water proof

CE approval

The products conforms to the EMC requirements for immunity and emission according to EN 50 08-1,

15.2 Nexus Network introduction and user policy

Introduction:

The Nexus Network is a Multi talker Multi receiver data bus specially designed for marine navigation applications. It utilises the RS485 standard with PLUS to 32 senders and/or receivers to form a Local Area Network. Data is transmitted synchronously with 1 start-bit, 8-data-bits, 1 parity-bit, two stop-bits in 9600 baud.

User policy:

The Nexus Network is open for new users and applications without the licence or a licence fee. The data bus however is, the property of the manufacturer, which means the specification must be followed in order to protect the manufacturer's commitments to the Nexus Network performance and safety.

For most PC-applications, the full dPLUSlex interface (Art. No. 21248), will be a very useful tool for monitoring real time data, to edit and store Waypoints to PC-file or to Server and/or to the NX2 GPS. The interface is sPLUSplied with a cable for connection from PC to the Server or NX2 instruments and/or the NX2 GPS. A 9-pole D-sub connector is connected to the RS232 port on the PC.

16 Optional Accessories

Below find a selection of optional accessories available. Please contact your local NX2 dealer for more information.

NX2 Completes

22118-3	Multi Control instrument and Server, 8m cable
22118-2	Multi Control and Server with Speed Log and depth transducer, 8m cable
22118-1	Speed log with log transducer, 8m cable
22118-4	Wind Data, with transducer, 25m cable, mast bracket
22118-5	Compass Data, with transducer 35°, 8 m cable
22118-6	GPS Navigator, with GPS Antenna, 8+10m cable

NX2/Nexus Transducers

22120-1	Server compl with 3m power cables
20707	Log/Temp transducer, 8 m cable (for Nexus and Star)
19915-8	Depth transducer, 8m cable (for NX2 only)
21731	Compass transducer 35°, 8m cable
20860	Compass transducer 45°, 8m cable
20721	Wind transducer, 25m cable, mast bracket
20721-1	CF-wind transducer, Carbon Fibre, 1260mm long, 380g, no mast cable incl.
20594	Nexus mast cable 25m
21721	MTC (Mast Twist Compensation) box, 8m cable, for Wind Data instr.
69980	MRC (Mast Rotation Sensor Compensation) box
21970	GPS Antenna, with NMEA 0183 output
21735	Bracket for GPS Antenna and 35° Compass transducer for bulkhead mount

NX2 Digital Instruments (all supplied with 0.2m cable)

22117-1	Speed log instrument
22117-3	Multi Control instrument
22117-4	Wind Data instrument
22117-5	Compass Data instrument
22117-6	GPS Navigator instrument
22117-7	Autopilot instrument

NX2 Analog Instruments (all supplied with 0.2m cable)

22115-01	NX2 Analog Wind Angle
22115-02	NX2 Analog Steer Pilot
22115-03	NX2 Analog Speed Trim
22115-05	NX2 Analog Speed 0-16kts
22115-06	NX2 Analog Speed 0-50kts
22115-07	NX2 Analog Depth 0-200m
22115-08	NX2 Analog Depth 0-600ft
22115-09	NX2 Analog Rudder angle
22115-10	NX2 Analog Compass
22115-11	NX2 Analog GPS Speed 0-16kts
22115-12	NX2 Analog GPS Speed 0-50kts
22115-13	NX2 Analog GPS Course

Nexus Remote Control Instrument

21210	Remote Control Instrument (RCI), with Autopilot control, 5m cable, bracket
21218-1	Bracket Remote Control instrument
20966	Connector 4-pole, NEW model (Allows cable - cable connection)

Nexus Multi XL

21680-1 Multi XL instrument, 4m cable (RCI or Multi Center needed to control Multi XL)
 21684-1 Multi XL Set, Multi XL instrument and Remote Control instrument
 69995 Mast bracket XL, in aluminium for Multi XL and Nexus / Star 110x110mm instr.

NX2 GPS

22118-6 GPS Navigator, with GPS Antenna, 8+10m cable
 22117-6 GPS Navigator instrument
 21970 GPS Antenna, with NMEA 0183 output
 20992-2 Bracket GPS Antenna, plastic with female thread 1" x 14 tpi
 21735 Bracket for GPS Antenna and 35° Compass transducer for bulkhead mount

Nexus Autopilot components

22117-7 Autopilot instrument
 21210 Remote Control instrument, with Autopilot control, 5m cable, bracket
 22115-09 NX2 Analog Rudder angle

21035-2 Servo Unit A-1510, 8m cable
 20860 Compass transducer 45°, 8m cable
 21731 Compass transducer 35°, 8m cable
 21036 Rudder Angle Transmitter RFU-25, 15m cable, ball joint linkage 230mm x 2
 69981 Linear Rudder Angle Transmitter

21134 Pumpset PF-0.3 12V
 21134-24 Pumpset PF-0.3 24V
 21341 Pumpset PF-0.3S 12V, with solenoid
 21341-24 Pumpset PF-0.3S 24V, with solenoid
 21136 Linear Drive AN-23, stroke 229mm, peak thrust 680kg
 69991-12 Integrated Linear Drive HP-40, stroke 254mm, peak thrust 500kg

17 Abbreviations

BSP	Boat Speed
BTW	Bearing To Waypoint
C	Celsius
F	Fahrenheit
KM	KiloMetre
KTS	KnoTS
MH	Miles per Hour
LCD	Liquid Crystal Display
LOW	LOW
MID	MID
MAX	MAX
RET	RETurn
SOG	Speed Over Ground
TRP	TRiP
-	Minus
+	Plus

WARRANTY**GENERAL**

All our products are designed and built to comply to the highest class industry standards. If the products are correctly installed, maintained and operated, as described in the installation and operation manual, they will provide long and reliable service. Our international Network of distributors can provide you with the information and assistance you may require virtually anywhere in the world.

Please read through and fill in this warranty card and send it to your national distributor for product registration.

LIMITED WARRANTY

The warranty covers repair of defective parts due to faulty Manufacturing and includes labour when repaired in the country of purchase. The warranty period is stated in the product manual, and commences from the date of purchase. The above warranty is the Manufacturer's only warranty and no other terms, expressed or implied, will apply. The Manufacturer specifically excludes the implied warranty of merchantability and fitness for a particular purpose.

CONDITIONS

- The supplied warranty card and receipt with proof of purchase date, must be shown to validate any warranty claim. Claims are to be made in accordance with the claims procedure outlined below.
- The warranty is non-transferrable and extends only to the original purchaser.
- The warranty does not apply to Products from which serial numbers have been removed, faulty installation or incorrect fusing, to conditions resulting from improper use, external causes, including service or modifications not performed by the Manufacturer or by its national distributors, or operation outside the environmental parameters specified for the Product.
- The Manufacturer will not compensate for consequential damage caused directly or indirectly by the malfunction of its equipment. The Manufacturer is not liable for any personal damage caused as a consequence of using its equipment.
- The Manufacturer, its national distributors or dealers are not liable for charges arising from sea trials, installation surveys or visits to the boat to attend to the equipment, whether under warranty or not. The right is reserved to charge for such services at an appropriate rate.
- The Manufacturer reserves the right to replace any products returned for repair, within the warranty period, with the nearest equivalent, if repair within a reasonable time period should not be possible.
- The terms and conditions of the warranty as described do not affect your statutory rights.

CLAIMS PROCEDURE

Equipment should be returned to the national distributor, or one of its appointed dealers, in the country where it was originally purchased. Valid claims will then be serviced and returned to the sender free of charge.

Alternatively, if the equipment is being used away from the country of purchase, it may be returned to the national distributor, or one of its appointed dealers, in the country where it is being used. In this case valid claims will cover parts only. Labour and return postage will be invoiced to the sender at an appropriate rate.

DISCLAIMER

Common sense must be used at all times when navigating and the Manufacturer's navigation equipment should only be considered as aids to navigation.

The Manufacturers policy of continuous improvement may result in changes to product specification without prior notice.

File id:

WARRANTY CARD
TO BE RETURNED TO YOUR NATIONAL DISTRIBUTOR

OWNER:

Name: _____

Street : _____

City/Zip Code : _____

Country: _____

Product name:

Serial number:

	A	B	C	1	2	3	4	5	6	7
_____	<input type="checkbox"/>									
_____	<input type="checkbox"/>									
_____	<input type="checkbox"/>									
_____	<input type="checkbox"/>									
_____	<input type="checkbox"/>									
_____	<input type="checkbox"/>									

Date of purchase: _____ Date installed _____

Dealers stamp:

Tick here if you do not wish to receive news about future products

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